

2.2 SEM

Scanning Electron Microscopy

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Introduction

Traditionally, the first instrument that would come to mind for small scale materials characterization would be the optical microscope. The optical microscope offered the scientist a first look at most samples and could be used to routinely document the progress of an investigation. As the sophistication of investigations increased, the optical microscope often has been replaced by instrumentation having superior spatial resolution or depth of focus. However, its use has continued because of the ubiquitous availability of the tool.

For the purpose of a detailed materials characterization, the optical microscope has been supplanted by two more potent instruments: the Transmission Electron Microscope (TEM) and the Scanning Electron Microscope (SEM). Because of its reasonable cost and the wide range of information that it provides in a timely manner, the SEM often replaces the optical microscope as the preferred starting tool for materials studies.

The SEM provides the investigator with a highly magnified image of the surface of a material that is very similar to what one would expect if one could actually “see” the surface visually. This tends to simplify image interpretations considerably, but

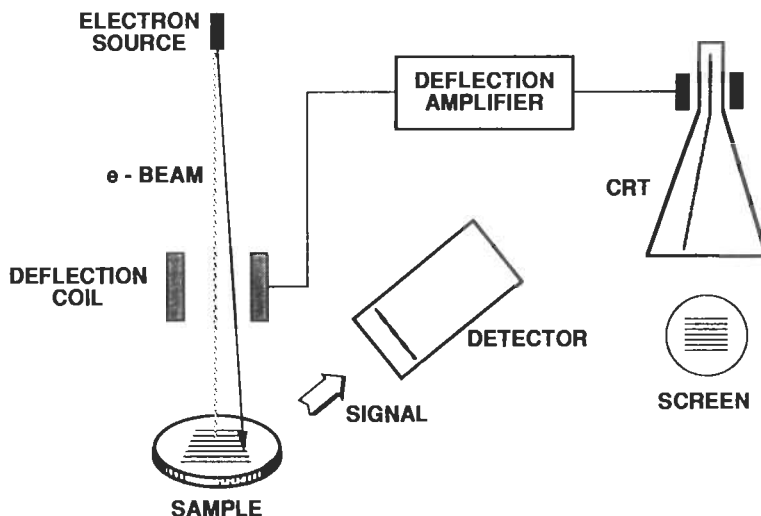


Figure 1 Schematic describing the operation of an SEM.

reliance on intuitive reactions to SEM images can, on occasion, lead to erroneous results. The resolution of the SEM can approach a few nm and it can operate at magnifications that are easily adjusted from about $10\times$ – $300,000\times$.

Not only is topographical information produced in the SEM, but information concerning the composition near surface regions of the material is provided as well. There are also a number of important instruments closely related to the SEM, notably the electron microprobe (EMP) and the scanning Auger microprobe (SAM). Both of these instruments, as well as the TEM, are described in detail elsewhere in this volume.

Physical Basis of Operation

In the SEM, a source of electrons is focused (in vacuum) into a fine probe that is rastered over the surface of the specimen, Figure 1. As the electrons penetrate the surface, a number of interactions occur that can result in the emission of electrons or photons from (or through) the surface. A reasonable fraction of the electrons emitted can be collected by appropriate detectors, and the output can be used to modulate the brightness of a cathode ray tube (CRT) whose x - and y -inputs are driven in synchronism with the x - y voltages rastering the electron beam. In this way an image is produced on the CRT; every point that the beam strikes on the sample is mapped directly onto a corresponding point on the screen. If the amplitude of the saw-tooth voltage applied to the x - and y -deflection amplifiers in the SEM is reduced by some factor while the CRT saw-tooth voltage is kept fixed at the level

necessary to produce a full screen display, the magnification, as viewed on the screen, will be increased by the same factor.

The principle images produced in the SEM are of three types: secondary electron images, backscattered electron images, and elemental X-ray maps. Secondary and backscattered electrons are conventionally separated according to their energies. They are produced by different mechanisms. When a high-energy primary electron interacts with an atom, it undergoes either inelastic scattering with atomic electrons or elastic scattering with the atomic nucleus. In an inelastic collision with an electron, some amount of energy is transferred to the other electron. If the energy transfer is very small, the emitted electron will probably not have enough energy to exit the surface. If the energy transferred exceeds the work function of the material, the emitted electron can exit the solid. When the energy of the emitted electron is less than about 50 eV, by convention it is referred to as a secondary electron (SE), or simply a *secondary*. Most of the emitted secondaries are produced within the first few nm of the surface. Secondaries produced much deeper in the material suffer additional inelastic collisions, which lower their energy and trap them in the interior of the solid.

Higher energy electrons are primary electrons that have been scattered without loss of kinetic energy (i.e., elastically) by the nucleus of an atom, although these collisions may occur after the primary electron has already lost some of its energy to inelastic scattering. Backscattered electrons (BSEs) are considered to be the electrons that exit the specimen with an energy greater than 50 eV, including Auger electrons. However most BSEs have energies comparable to the energy of the primary beam. The higher the atomic number of a material, the more likely it is that backscattering will occur. Thus as a beam passes from a low- Z (atomic number) to a high- Z area, the signal due to backscattering, and consequently the image brightness, will increase. There is a built in contrast caused by elemental differences.

One further breaks down the secondary electron contributions into three groups: SEI, SEII and SEIII. SEIs result from the interaction of the incident beam with the sample at the point of entry. SEIIs are produced by BSEs on exiting the sample. SEIIIs are produced by BSEs which have exited the surface of the sample and further interact with components on the interior of the SEM usually not related to the sample. SEIIs and SEIIIs come from regions far outside that defined by the incident probe and can cause serious degradation of the resolution of the image.

It is usual to define the primary beam current i_0 , the BSE current i_{BSE} , the SE current i_{SE} , and the sample current transmitted through the specimen to ground i_{SC} , such that the Kirchoff current law holds:

$$i_0 = i_{\text{BSE}} + i_{\text{SE}} + i_{\text{SC}} \quad (1)$$

These signals can be used to form complementary images. As the beam current is increased, each of these currents will also increase. The backscattered electron yield η and the secondary electron yield δ , which refer to the number of backscattered and secondary electrons emitted per incident electron, respectively, are defined by the relationships:

$$\eta = \frac{i_{\text{BSE}}}{i_0} \quad (2)$$

$$\delta = \frac{i_{\text{SE}}}{i_0} \quad (3)$$

In most currently available SEMs, the energy of the primary electron beam can range from a few hundred eV up to 30 keV. The values of δ and η will change over this range, however, yielding micrographs that may vary in appearance and information content as the energy of the primary beam is changed. The value of the BSE yield increases with atomic number Z , but its value for a fixed Z remains constant for all beam energies above 5 keV. The SE yield δ decreases slowly with increasing beam energy after reaching a peak at some low voltage, usually around 1 keV. For any fixed voltage, however, δ shows very little variation over the full range of Z . Both the secondary and backscattered electron yields increase with decreasing glancing angle of incidence because more scattering occurs closer to the surface. This is one of the major reasons why the SEM provides excellent topographical contrast in the SE mode; as the surface changes its slope, the number of secondary electrons produced changes as well. With the BSEs this effect is not as prominent, since to fully realize it the BSE detector would have to be repositioned to measure forward scattering.

An additional electron interaction of major importance in the SEM occurs when the primary electron collides with and ejects a core electron from an atom in the solid. The excited atom will decay to its ground state by emitting either a characteristic X-ray photon or an Auger electron (see the article on AES). The X-ray emission signal can be sorted by energy in an energy dispersive X-ray detector (see the article on EDS) or by wavelength with a wavelength spectrometer (see the article on EPMA). These distributions are characteristic of the elements that produced them and the SEM can use these signals to produce elemental images that show the spatial distribution of particular elements in the field of view. The primary electrons can travel considerable distances into a solid before losing enough energy through collisions to be no longer able to excite X-ray emission. This means that a large volume of the sample will produce X-ray emission for any position of the smaller primary beam, and consequently the spatial resolution of this type of image will rarely be better than 0.5 μm .

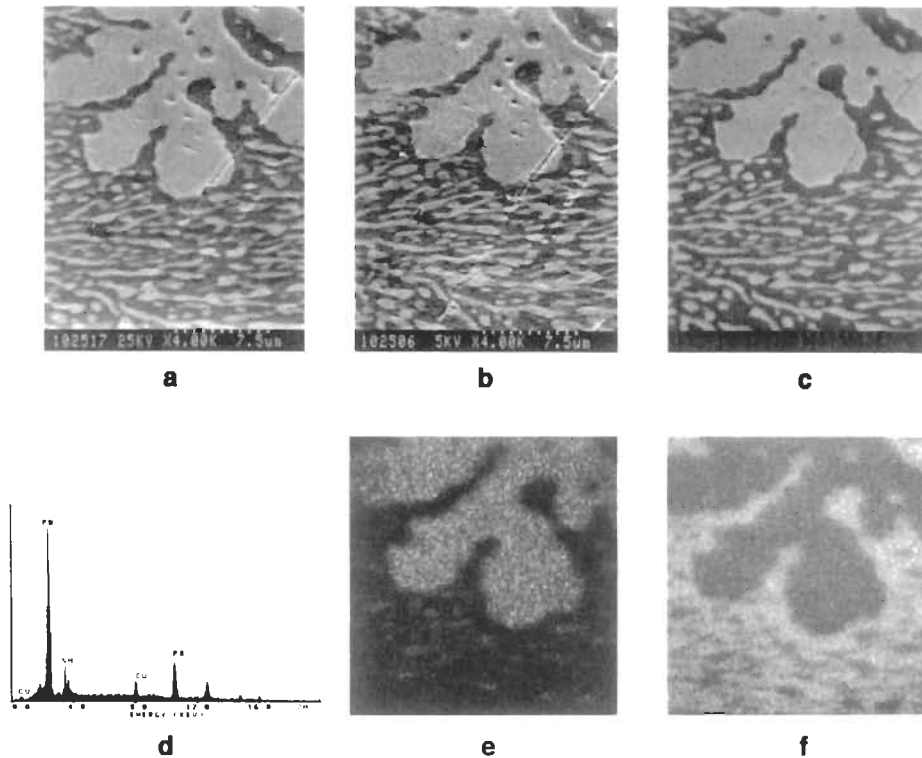


Figure 2 Micrographs of the same region of a specimen in various imaging modes on a high-resolution SEM: (a) and (b) SE micrographs taken at 25 and 5 keV, respectively; (c) backscattered image taken at 25 keV; (d) EDS spectrum taken from the Pb-rich phase of the Pb-Sn solder; (e) and (f) elemental maps of the two elements taken by accepting only signals from the appropriate spectral energy regions.

An illustration of this discussion can be seen in Figure 2, which is a collection of SEM images taken from the surface of a Pb-Sn solder sample contaminated with a low concentration of Cu. Figure 1a, a secondary electron image (SE) taken with a primary energy of 25 keV, distinguishes the two Pb-Sn eutectic phases as brighter regions (almost pure Pb) separated by darker bands corresponding to the Sn-rich phase. The micrograph originally was taken at a magnification of 4000 \times but care should be exercised when viewing published examples because of the likelihood of photographic enlargement or reduction by the printer. Most SEMs produce a marker directly on the photograph that defines the actual magnification. In the present example, the series of dots at the bottom of the micrograph span a physical distance of 7.5 μm . This can be used as an internally consistent ruler for measurement purposes.

The micrograph also shows the presence of a scratch that goes diagonally across the entire field of view. Note the appearance of depth to this scratch as a result of the variation in secondary electron yield with the local slope of the surface. The spatial resolution of the SEM due to SEIs usually improves with increasing energy of the primary beam because the beam can be focused into a smaller spot. Conversely, at higher energies the increased penetration of the electron beam into the sample will increase the interaction volume, which may cause some degradation of the image resolution due to SEIIs and SEIIIs. This is shown in Figure 2b, which is a SE image taken at only 5 keV. In this case the reduced electron penetration brings out more surface detail in the micrograph.

There are two ways to produce a backscattered electron image. One is to put a grid between the sample and the SE detector with a -50-V bias applied to it. This will repel the SEs since only the BSEs will have sufficient energy to penetrate the electric field of the grid. This type of detector is not very effective for the detection of BSEs because of its small solid angle of collection. A much larger solid angle of collection is obtained by placing the detector immediately above the sample to collect the BSE. Two types of detectors are commonly used here. One type uses partially depleted n-type silicon diodes coated with a layer of gold, which convert the incident BSEs into electron-hole pairs at the rate of 1 pair per 3.8 eV. Using a pair of Si detectors makes it possible to separate atomic number contrast from topographical contrast. The other detector type, the so-called scintillator photo multiplier detector, uses a material that will fluoresce under the bombardment of the high-energy BSEs to produce a light signal that can be further amplified. The photomultiplier detector was used to produce the BSE micrograph in Figure 2c. Since no secondary electrons are present, the surface topography of the scratch is no longer evident and only atomic number contrast appears.

Atomic number contrast can be used to estimate concentrations in binary alloys because the actual BSE signal increases somewhat predictably with the concentration of the heavier element of the pair.

Both energy-dispersive and wavelength-dispersive X-ray detectors can be used for elemental detection in the SEM. The detectors produce an output signal that is proportional to the number of X-ray photons in the area under electron bombardment. With an EDS the output is displayed as a histogram of counts versus X-ray energy. Such a display is shown in Figure 2d. This spectrum was produced by allowing the electron beam to dwell on one of the Pb-rich areas of the sample. The spectrum shows the presence of peaks corresponding to Pb and a small amount of Sn. Since this sample was slightly contaminated with Cu, the small Cu peak at 8 keV is expected. The detectors can be adjusted to pass only a range of pulses corresponding to a single X-ray spectral peak that is characteristic of a particular element. This output can then be used to produce an elemental image or an X-ray map; two X-ray maps using an EDS are shown in Figure 2e for Pb and in Figure 2f for Sn. Note the complementary nature of these images, and how easy it is to iden-

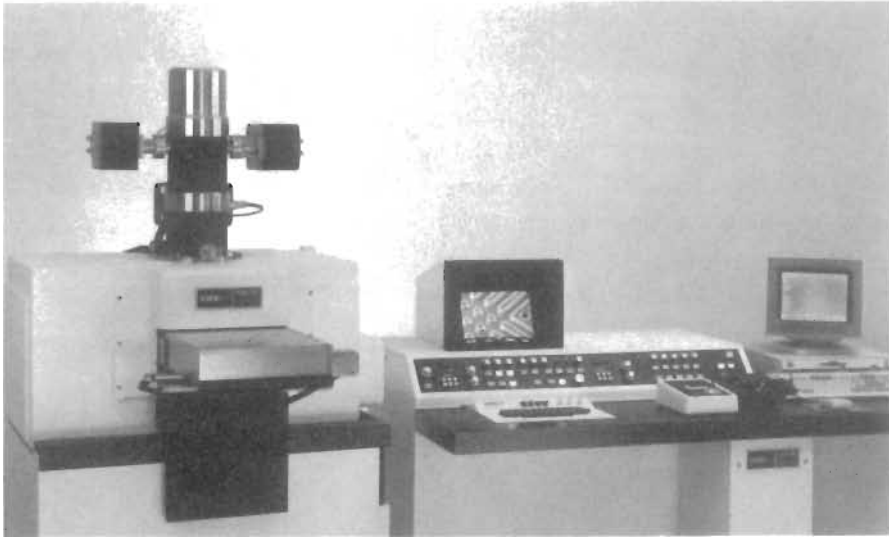


Figure 3 Photograph of a modern field emission SEM. (Courtesy of AMRAY Inc., Bedford, MA)

tify portions of the SE or BSE image having specific local compositions. The data usually can be quantified through the use of appropriate elemental standards and well-established computational algorithms.

Instrumentation

Figure 3 shows a photograph of a recent model SEM. The main features of the instrument are the electron column containing the electron source (i.e., the gun), the magnetic focusing lenses, the sample vacuum chamber and stage region (at the bottom of the column) and the electronics console containing the control panel, the electronic power supplies and the scanning modules. A solid state EDS X-ray detector is usually attached to the column and protrudes into the area immediately above the stage; the electronics for the detector are in separate modules, but there has been a recent trend toward integration into the SEM system architecture.

The overall function of the electron gun is to produce a source of electrons emanating from as small a “spot” as possible. The lenses act to demagnify this spot and focus it onto a sample. The gun itself produces electron emission from a small area and then demagnifies it initially before presenting it to the lens stack. The actual emission area might be a few μm in diameter and will be focused eventually into a spot as small as 1 or 2 nm on the specimen.

There are three major types of electron sources: thermionic tungsten, LaB_6 , and hot and cold field emission. In the first case, a tungsten filament is heated to allow

electrons to be emitted via thermionic emission. Temperatures as high as 3000° C are required to produce a sufficiently bright source. These filaments are easy to work with but have to be replaced frequently because of evaporation. The material LaB₆ has a lower work function than tungsten and thus can be operated at lower temperatures, and it yields a higher source brightness. However, LaB₆ filaments require a much better vacuum than tungsten to achieve good stability and a longer lifetime. The brighter the source, the higher the current density in the spot, which consequently permits more electrons to be focused onto the same area of a specimen. Recently, field emission electron sources have been produced. These tips are very sharp; the strong electric field created at the tip extracts electrons from the source even at low temperatures. Emission can be increased by thermal assistance but the energy width of the emitted electrons may increase somewhat. The sharper the energy profile, the less the effect of chromatic aberrations of the magnetic defocusing lenses. Although they are more difficult to work with, require very high vacuum and occasional cleaning and sharpening via thermal flashing, the enhanced resolution and low voltage applications of field emission tips are making them the source of choice in newer instruments that have the high-vacuum capability necessary to support them.

The beam is defocused by a series of magnetic lenses as shown in Figure 4. Each lens has an associated defining aperture that limits the divergence of the electron beam. The top lenses are called *condenser* lenses, and often are operated as if they were a single lens. By increasing the current through the condenser lens, the focal length is decreased and the divergence increases. The lens therefore passes less beam current on to the next lens in the chain. Increasing the current through the first lens reduces the size of the image produced (thus the term spot size for this control). It also spreads out the beam resulting in beam current control as well. Smaller spot sizes, often given higher dial numbers to correspond with the higher lens currents required for better resolution, are attained with less current (signal) and a smaller signal-to-noise ratio. Very high magnification images therefore are inherently noisy.

The beam next arrives at the final lens–aperture combination. The final lens does the ultimate focusing of the beam onto the surface of the sample. The sample is attached to a specimen stage that provides *x*- and *y*-motion, as well as tilt with respect to the beam axis and rotation about an axis normal to the specimen's surface. A final “*z*” motion allows for adjustment of the distance between the final lens and the sample's surface. This distance is called the *working distance*.

The working distance and the limiting aperture size determine the convergence angle shown in the figure. Typically the convergence angle is a few mrad and it can be decreased by using a smaller final aperture or by increasing the working distance. The smaller the convergence angle, the more variation in the *z*-direction topography that can be tolerated while still remaining in focus to some prescribed degree. This large depth of focus contributes to the ease of observation of topographical

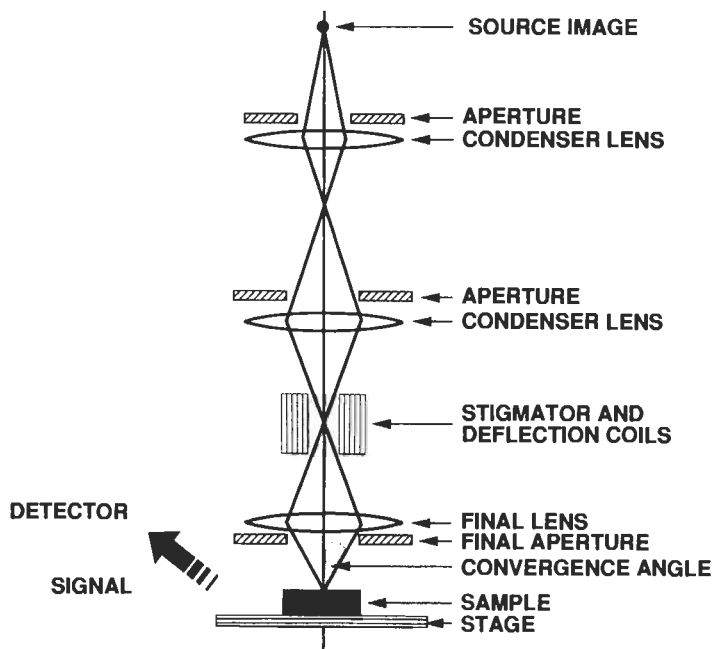


Figure 4 Schematic of the electron optics constituting the SEM.

effects. The depth of focus in the SEM is compared in Figure 5 with that of an optical microscope operated at the same magnification for viewing the top of a common machine screw.

Sample Requirements

The use of the SEM requires very little in regard to sample preparation, provided that the specimen is vacuum compatible. If the sample is conducting, the major limitation is whether it will fit onto the stage or, for that matter, into the specimen chamber. For special applications, very large stage–vacuum chamber combinations have been fabricated into which large forensic samples (such as boots or weapons) or 8-in diameter semiconductor wafers can be placed. For the latter case, special final lenses having conical shapes have been developed to allow for observation of large tilted samples at reasonably small working distances.

If the sample is an insulator there are still methods by which it can be studied in the instrument. The simplest approach is to coat it with a thin (10-nm) conducting film of carbon, gold, or some other metal. In following this approach, care must be taken to avoid artifacts and distortions that could be produced by nonuniform coatings or by agglomeration of the coating material. If an X-ray analysis is to be

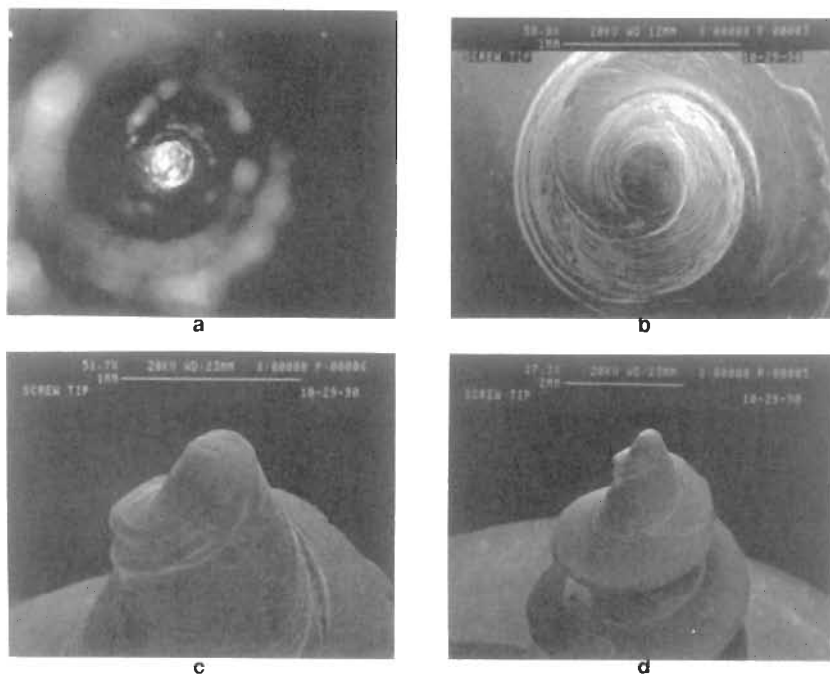


Figure 5 Micrographs of a machine screw illustrating the great depth of field of the SEM: (a) optical micrograph of the very tip of the screw; (b) and (c) the same area in the SEM and a second image taken at an angle (the latter shows the depth of field quite clearly); (d) lower magnification image.

made on such a coated surface, care must be taken to exclude or correct for any X-ray peaks generated in the deposited material.

Uncoated insulating samples also can be studied by using low primary beam voltages (< 2.0 keV) if one is willing to compromise image resolution to some extent. If we define the total electron yield as $\sigma = \delta + \eta$, then when $\sigma < 1$ we either must supply or remove electrons from the specimen to avoid charge build-up. Conduction to ground automatically takes care of this problem for conducting samples, but for insulators this does not occur. Consequently, one might expect it to be impossible to study insulating samples in the SEM. The way around this difficulty is suggested in Figure 6 which plots σ as a function of energy of the incident electron. The yield is seen to rise from 0 to some amount greater than 1 and then to decrease back below 1 as the energy increases. The two energy crossovers E_1 and E_2 , between which minimal charging occurs, are often quite low, typically less than 2.0 keV.

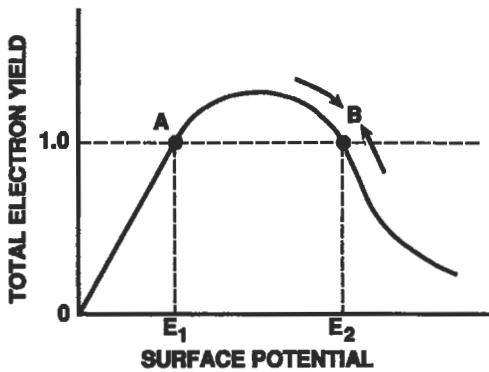


Figure 6 Total electron yield as a function of the primary electron's energy when it arrives at the surface of the specimen.

The energy scale in the figure is actually meant to depict the energy of the electron as it arrives at the surface. Because of charging, the electron's energy may be greater or less than the accelerating voltage would suggest. Consider electrons striking the surface with an energy near E_2 as identified by point B in the figure. If the energy is somewhat below that of the crossover point, the total electron yield will be greater than 1 and the surface will be positively charged, thereby attracting incoming electrons and increasing the effective energy of the primary beam. The electron's energy will continue to increase until E_2 is reached. If it overshoots, the yield will drop and some negative charging will begin until, again, a balance is reached at point B. Point B is therefore a stable operating point for the insulator in question, and operating around this point will allow excellent micrographs to be produced. E_1 (point A) does not represent a stable operating condition.

If the sample is a metal that has been coated with a thin oxide layer, a higher accelerating voltage might actually improve the image. The reason for this is that as the high-energy beam passes through the oxide, it can create electron-hole pairs in sufficient numbers to establish local conduction. This effect is often noted while observing semiconductor devices that have been passivated with thin deposited oxide films.

Applications

We have already discussed a number of applications of the SEM to materials characterization: topographical (SE) imaging, Energy-Dispersive X-Ray analysis (EDS) and the use of backscattering measurements to determine the composition of binary alloy systems. We now shall briefly discuss applications that are, in part, spe-

cific to certain industries or technologies. Although there is significant literature on applications of the SEM to the biological sciences, such applications will not be covered in this article.

At magnifications above a few thousand, the raster scanning of the beam is very linear, resulting in a constant magnification over the entire image. This is not the case at low magnifications, where significant nonlinearity may be present. Uniform magnification allows the image to be used for very precise size measurements. The SEM therefore can be a very accurate and precise metrology tool. This requires careful calibration using special SEM metrology standards available from the National Institute of Standards and Technology.

The fact that the SE coefficient varies in a known way with the angle that the primary beam makes with the surface allows the approximate determination of the depth (z) variation of the surface morphology from the information collected in a single image. By tilting the specimen slightly ($5\text{--}8^\circ$), stereo pairs can be produced that provide excellent quality three-dimensional images via stereoscopic viewers. Software developments now allow these images to be calculated and displayed in three-dimension-like patterns on a computer screen. Contour maps can be generated in this way. The computer-SEM combination has been very valuable for the analysis of fracture surfaces and in studies of the topography of in-process integrated circuits and devices.

Computers can be used both for image analysis and image processing. In the former case, size distributions of particles or features, and their associated measurement parameters (area, circumference, maximum or minimum diameters, etc.) can be obtained easily because the image information is collected via digital scanning in a way that is directly compatible with the architecture of image analysis computers. In these systems an image is a stored array of 500×500 signal values. Larger arrays are also possible with larger memory capacity computers.

Image processing refers to the manipulation of the images themselves. This allows for mathematical smoothing, differentiation, and even image subtraction. The contrast and brightness in an image can be adjusted in a linear or nonlinear manner and algorithms exist to highlight edges of features or to completely suppress background variations. These methods allow the microscopist to extract the maximum amount of information from a single micrograph. As high-speed PCs and workstations continue to decrease in price while increasing in capacity, these applications will become more commonplace.

Electronics has, in fact, been a very fertile area for SEM application. The energy distribution of the SEs produced by a material in the SEM has been shown to shift linearly with the local potential of the surface. This phenomenon allows the SEM to be used in a noncontact way to measure voltages on the surfaces of semiconductor devices. This is accomplished using energy analysis of the SEs and by directly measuring these energy shifts. The measurements can be made very rapidly so that circuit waveforms at particular internal circuit nodes can be determined accurately.

Very high frequency operation of circuits can be observed by using stroboscopic techniques, blanking the primary beam at very high frequencies and by collecting information only during small portions of the operating cycle. By sliding the viewing window over the entire cycle, a waveform can be extracted with surprising sensitivity and temporal resolution. Recently, special SEM instruments have been designed that can observe high-speed devices under nominal operating conditions. The cost of these complex electron beam test systems can exceed \$1,000,000.

Actually, any physical process that can be induced by the presence of an electron beam and that can generate a measurable signal can be used to produce an image in the SEM. For example, when a metal film is deposited on a clean semiconductor surface, a region of the semiconductor next to the metal can be depleted of mobile charge. This depletion region can develop a strong electric field. Imagine the metal to be connected through a current meter to the back side of the semiconductor surface. No current will flow, of course, but we can turn on an electron beam that penetrates the metal and allows the impinging electrons to create electron-hole pairs. The electric field will separate these carriers and sweep them out of the depletion region, thereby generating a current. Among other things, the current will be determined by the perfection or the chemistry of the spot where the beam strikes. By scanning the beam in the SEM mode, an image of the perfection (or chemistry) of the surface can be generated. This is referred to as electron beam-induced conductivity, and it has been used extensively to identify the kinds of defects that can affect semiconductor device operation.

The SEM can also be used to provide crystallographic information. Surfaces that to exhibit grain structure (fracture surfaces, etched, or decorated surfaces) can obviously be characterized as to grain size and shape. Electrons also can be channeled through a crystal lattice and when channeling occurs, fewer backscattered electrons can exit the surface. The channeling patterns so generated can be used to determine lattice parameters and strain.

The X-rays generated when an electron beam strikes a crystal also can be diffracted by the specimen in which they are produced. If a photograph is made of this diffraction pattern (the Kossel pattern) using a special camera, localized crystallographic information can be gleaned.

Further applications abound. Local magnetic fields affect the trajectories of the SEs as well as the BSEs, making the SEM a useful tool for observing the magnetic domains of ferromagnetic materials, magnetic tapes, and disk surfaces. Pulsed electron beams generate both thermal and acoustic signals which can be imaged to provide mechanical property maps of materials. Some semiconductors and oxides produce photons in the ultraviolet, visible, or infrared regions, and these cathodoluminescence signals provide valuable information about the electronic properties of these materials. The application of this method to semiconductor lasers or LED devices is probably self-evident. Even deep-level transient spectroscopy, a method that is particularly difficult to interpret and that provides information about impu-

rities having energy levels within the band gap of semiconductors, has been used to produce images in the SEM.

Conclusions

Every month a new application for the SEM appears in the literature, and there is no reason to assume that this growth will cease. The SEM is one of the more versatile of analytical instruments and it is often the first expensive instrument that a characterization laboratory will purchase.

As time goes on, the ultimate resolution of the SEM operated in these modes will probably level out near 1 nm. The major growth of SEMs now seems to be in the development of specialized instruments. An environmental SEM has been developed that uses differential pumping to permit the observation of specimens at higher pressures. Photographs of the formation of ice crystals have been taken and the instrument has particular application to samples that are not vacuum compatible, such as biological samples.

Other instruments have been described that have application in the electronics field. Special metallurgical hot and cold stages are being produced, and stages capable of large motions with sub- μm accuracy and reproducibility will become common.

Computers will be integrated more and more into commercial SEMs and there is an enormous potential for the growth of computer supported applications. At the same time, related instruments will be developed and extended, such as the scanning ion microscope, which uses liquid-metal ion sources to produce finely focused ion beams that can produce SEs and secondary ions for image generation. The contrast mechanisms that are exhibited in these instruments can provide new insights into materials analysis.

Related Articles in the Encyclopedia

TEM, STEM, EDS, EPMA, Surface Roughness, AES, and CL

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2.3 STM and SFM

Scanning Tunneling Microscopy and Scanning Force Microscopy

REBECCA S. HOWLAND AND MICHAEL D. KIRK

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Introduction

Scanning Tunneling Microscopy (STM) and its offspring, Scanning Force Microscopy (SFM), are real-space imaging techniques that can produce topographic images of a surface with atomic resolution in all three dimensions. Almost any solid surface can be studied with STM or SFM: insulators, semiconductors, and conductors, transparent as well as opaque materials. Surfaces can be studied in air, in liquid, or in ultrahigh vacuum, with fields of view from atoms to greater than $250 \times 250 \mu\text{m}$. With this flexibility in both the operating environment and types of samples that can be studied, STM/SFM is a powerful imaging system.

The scanning tunneling microscope was invented at IBM, Zurich, by Gerd Binnig and Heinrich Rohrer in 1981.¹ In ultrahigh vacuum, they were able to resolve the atomic positions of atoms on the surface of Si (111) that had undergone a 7×7 reconstruction (Figure 1). With this historic image they solved the puzzle of the atomic structure of this well studied surface, thereby establishing firmly the credibility and importance of this form of microscopy. For the invention of STM, Binnig and Rohrer earned the Nobel Prize for Physics in 1986.

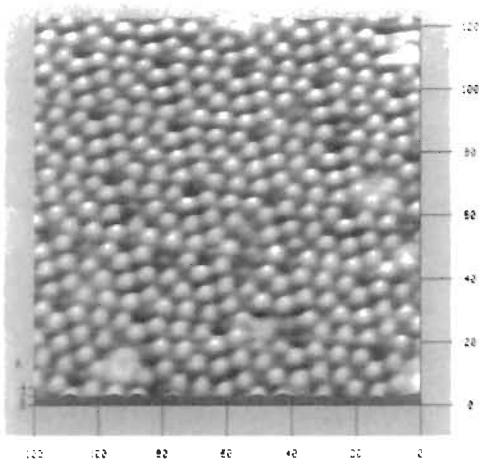


Figure 1 Ultrahigh-vacuum STM image of Si (111) showing 7×7 reconstruction.

Since then, STM has been established as an instrument for forefront research in surface physics. Atomic resolution work in ultrahigh vacuum includes studies of metals, semimetals and semiconductors. In particular, ultrahigh-vacuum STM has been used to elucidate the reconstructions that Si, as well as other semiconducting and metallic surfaces undergo when a submonolayer to a few monolayers of metals are adsorbed on the otherwise pristine surface.²

Because STM measures a quantum-mechanical tunneling current, the tip must be within a few Å of a conducting surface. Therefore any surface oxide or other contaminant will complicate operation under ambient conditions. Nevertheless, a great deal of work has been done in air, liquid, or at low temperatures on inert surfaces. Studies of adsorbed molecules on these surfaces (for example, liquid crystals on highly oriented, pyrolytic graphite³) have shown that STM is capable of even atomic resolution on organic materials.

The inability of STM to study insulators was addressed in 1985 when Binnig, Christoph Gerber and Calvin Quate invented a related instrument, the scanning force microscope.⁴ Operation of SFM does not require a conducting surface; thus insulators can be studied without applying a destructive coating. Furthermore, studying surfaces in air is feasible, greatly simplifying sample preparation while reducing the cost and complexity of the microscope.

STM and SFM belong to an expanding family of instruments commonly termed Scanning Probe Microscopes (SPMs). Other common members include the magnetic force microscope, the scanning capacitance microscope, and the scanning acoustic microscope.⁵

Although the first six or seven years of scanning probe microscope history involved mostly atomic imaging, SPMs have evolved into tools complementary to Scanning and Transmission Electron Microscopes (SEMs and TEMs), and optical and stylus profilometers. The change was brought about chiefly by the introduction of the ambient SFM and by improvements in the range of the piezoelectric scanners that move the tip across the sample. With lateral scan ranges on the order of 250 μm , and vertical ranges of about 15 μm , STM and SFM can be used to address larger scale problems in surface science and engineering in addition to atomic-scale research. STM and SFM are commercially available, with several hundred units in place worldwide.

SPMs are simpler to operate than electron microscopes. Because the instruments can operate under ambient conditions, the set-up time can be a matter of minutes. Sample preparation is minimal. SFM does not require a conducting path, so samples can be mounted with double-stick tape. STM can use a sample holder with conducting clips, similar to that used for SEM. An image can be acquired in less than a minute; in fact, "movies" of ten frames per second have been demonstrated.⁶

The three-dimensional, quantitative nature of STM and SFM data permit in-depth statistical analysis of the surface that can include contributions from features 10 nm across or smaller. By contrast, optical and stylus profilometers average over areas a few hundred \AA across at best, and more typically a μm . Vertical resolution for SFM/STM is sub- \AA , better than that of other profilometers. STM and SFM are excellent high-resolution profilometers.

STM and SFM are free from many of the artifacts that afflict other kinds of profilometers. Optical profilometers can experience complicated phase shifts when materials with different optical properties are encountered. The SFM is sensitive to topography only, independent of the optical properties of the surface. (STM may be sensitive to the optical properties of the material inasmuch as optical properties are related to electronic structure.) The tips of traditional stylus profilometers exert forces that can damage the surfaces of soft materials, whereas the force on SFM tips is many orders of magnitude lower. SFM can image even the tracks left by other stylus profilometers.

In summary, scanning probe microscopes are research tools of increasing importance for atomic-imaging applications in surface science. In addition, SFM and STM are now used in many applications as complementary techniques to SEM, TEM, and optical and stylus profilometry. They meet or exceed the performance of these instruments under most conditions, and have the advantage of operating in an ambient environment with little or no sample preparation. The utility of scanning probe microscopy to the magnetic disk, semiconductor, and the polymer industries is gaining recognition rapidly. Further industrial applications include the analysis of optical components, mechanical parts, biological samples, and other areas where quality control of surfaces is important.

Basic Principles

STM

Scanning tunneling microscopes use an atomically sharp tip, usually made of tungsten or Pt-Ir. When the tip is within a few Å of the sample's surface, and a bias voltage V_t is applied between the sample and the tip, quantum-mechanical tunneling takes place across the gap. This tunneling current I_t depends exponentially on the separation d between the tip and the sample, and linearly on the local density of states. The exponential dependence of the magnitude of I_t upon d means that, in most cases, a single atom on the tip will image the single nearest atom on the sample surface.

The quality of STM images depends critically on the mechanical and electronic structure of the tip. Tungsten tips are sharpened by electrochemical etching, and can be used for a few hours in air, until they oxidize. On the other hand, Pt-Ir tips can be made by stretching a wire and cutting it on an angle with wire cutters. These tips are easy to make and slow to oxidize, but the resulting tip does not have as high an aspect ratio as a tungsten tip. As a result, Pt-Ir tips are not as useful for imaging large structures.

In its most common mode of operation, STM employs a piezoelectric transducer to scan the tip across the sample (Figure 2a). A feedback loop operates on the scanner to maintain a constant separation between the tip and the sample. Monitoring the position of the scanner provides a precise measurement of the tip's position in three dimensions. The precision of the piezoelectric scanning elements, together with the exponential dependence of I_t upon d means that STM is able to provide images of individual atoms.

Because the tunneling current also depends on the local density of states, STM can be used for spatially resolved spectroscopic measurements. When the component atomic species are known, STM can differentiate among them by recording and comparing multiple images taken at different bias voltages. One can ramp the bias voltage between the tip and the sample and record the corresponding change in the tunneling current to measure I versus V or dI/dV versus V at specific sites on the image to learn directly about the electronic properties of the surface. Such measurements give direct information on the local density of electronic states. This technique was pioneered by Hamers, et al., who used tunneling spectroscopy to map the local variations in the bonding structure between Si atoms on a reconstructed surface.⁷

On the other hand, the sensitivity of STM to electronic structure can lead to undesired artifacts when the surface is composed of regions of varying conductivity. For example, an area of lower conductivity will be represented as a dip in the image. If the surface is not well known, separating topographic effects from electronic effects can be difficult.

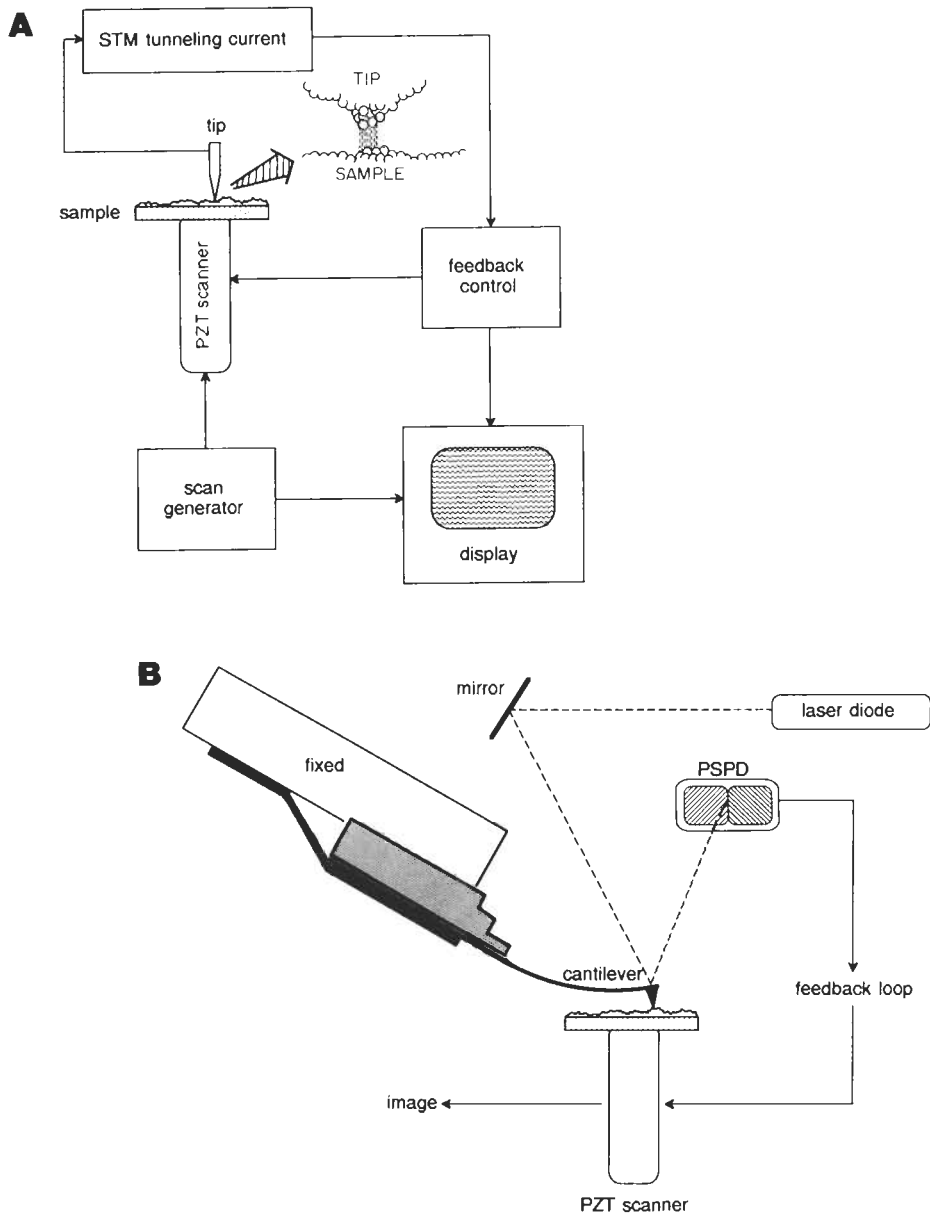


Figure 2 Schematic of STM (a) and SFM (b).

SFM

Scanning force microscopes use a sharp tip mounted on a flexible cantilever. When the tip comes within a few Å of the sample's surface, repulsive van der Waals forces

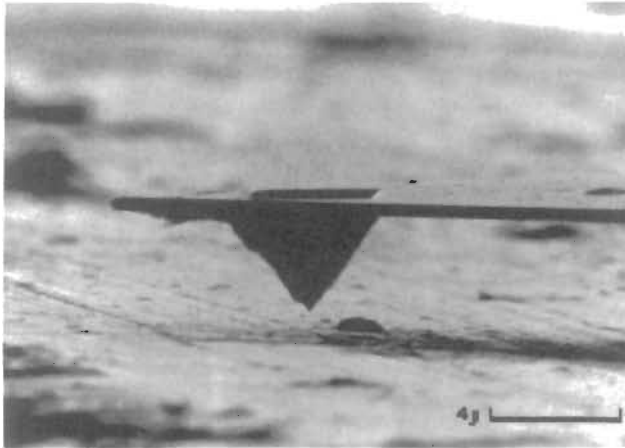


Figure 3 SEM image of SFM cantilever showing pyramidal tip.

between the atoms on the tip and those on the sample cause the cantilever to deflect. The magnitude of the deflection depends on the tip-to-sample distance d . However, this dependence is a power law, that is not as strong as the exponential dependence of the tunneling current upon d employed by STM. Thus several atoms on an SFM tip will interact with several atoms on the surface. Only with an unusually sharp tip and flat sample is the lateral resolution truly atomic; normally the lateral resolution of SFM is about 1 nm.

Like STM, SFM employs a piezoelectric transducer to scan the tip across the sample (Figure 2b), and a feedback loop operates on the scanner to maintain a constant separation between the tip and the sample. As with STM, the image is generated by monitoring the position of the scanner in three dimensions.

For SFM, maintaining a constant separation between the tip and the sample means that the deflection of the cantilever must be measured accurately. The first SFM used an STM tip to tunnel to the back of the cantilever to measure its vertical deflection. However, this technique was sensitive to contaminants on the cantilever.⁴ Optical methods proved more reliable. The most common method for monitoring the deflection is with an optical-lever or beam-bounce detection system.⁸ In this scheme, light from a laser diode is reflected from the back of the cantilever into a position-sensitive photodiode. A given cantilever deflection will then correspond to a specific position of the laser beam on the position-sensitive photodiode. Because the position-sensitive photodiode is very sensitive (about 0.1 Å), the vertical resolution of SFM is sub-Å.

Figure 3 shows an SEM micrograph of a typical SFM cantilever. The cantilevers are 100–200 μm long and 0.6 μm thick, microfabricated from low-stress Si₃N₄ with an integrated, pyramidal tip. Despite a minimal tip radius of about 400 Å,

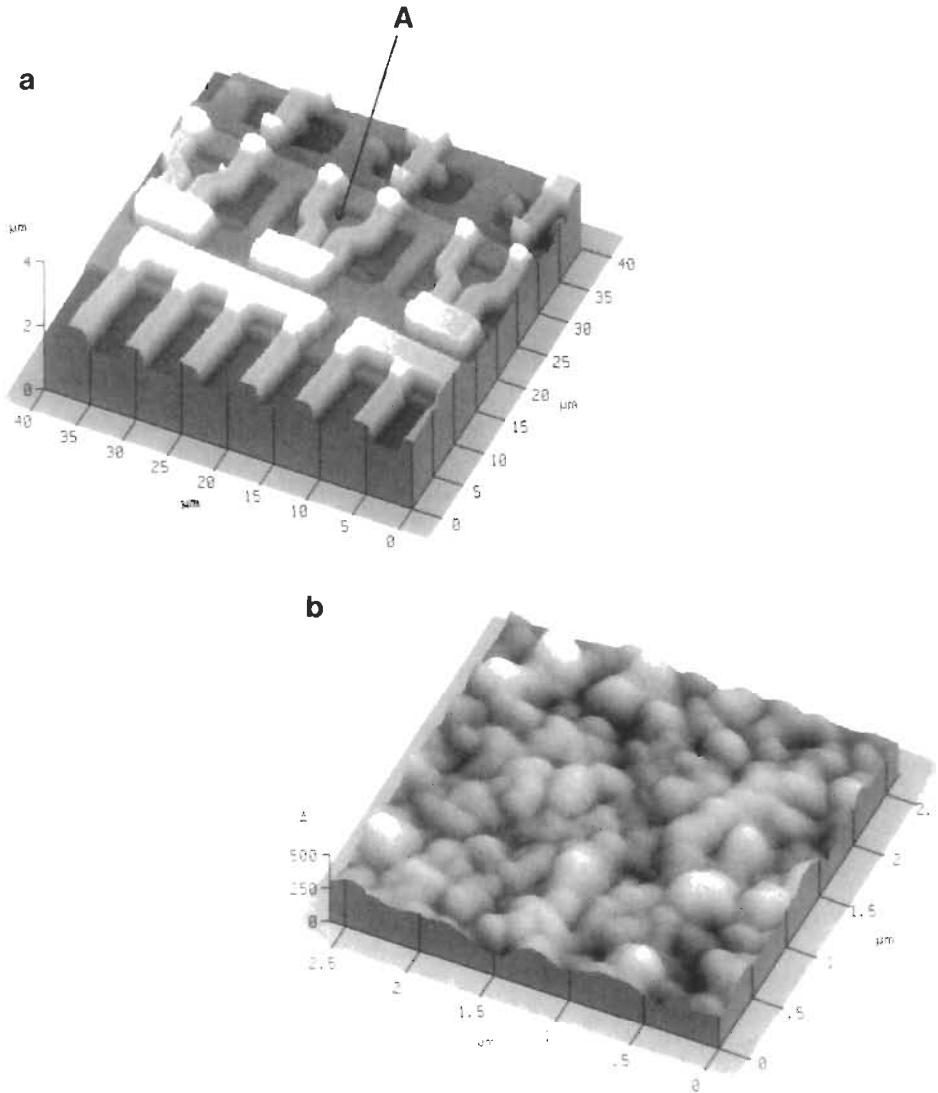


Figure 4 SFM image of an integrated circuit (a) and close-up of silicon oxide on its surface (b).

which is needed to achieve high lateral resolution, the pressure exerted on the sample surface is small because of the low force constant of the cantilever (typically 0.2 N/m), and the high sensitivity of the position-sensitive photodiode to cantilever deflection. The back of the cantilever may be coated with gold or another metal to enhance the reflectance of the laser beam into the detector.

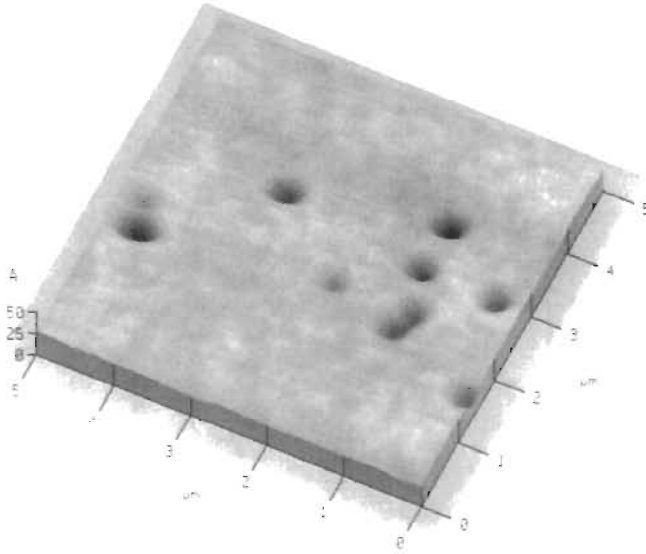


Figure 5 SFM image of oxidized Si wafer showing pinhole defects 20 Å deep.

Common Modes of Analysis and Examples

STM and SFM are most commonly used for topographic imaging, three-dimensional profilometry and spectroscopy (STM only).

Topography

Unlike optical or electron microscopes, which rely on shadowing to produce contrast that is related to height, STM and SFM provide topographic information that is truly three-dimensional. The data are digitally stored, allowing the computer to manipulate and display the data as a three-dimensional rendition, viewed from any altitude and azimuth. For example, Figure 4a shows an SFM image of an integrated circuit; Figure 4b is a close-up of the oxide on the surface of the chip in the region marked *A* in Figure 4a. In a similar application, Figure 5 is an SFM image of a Si wafer with pinholes, 20 Å deep. Easily imaged with SFM, these pinholes cannot be detected with SEM.

Profilometry

The three-dimensional, digital nature of SFM and STM data makes the instruments excellent high-resolution profilometers. Like traditional stylus or optical profilometers, scanning probe microscopes provide reliable height information. However, traditional profilometers scan in one dimension only and cannot match SPM's height and lateral resolution.

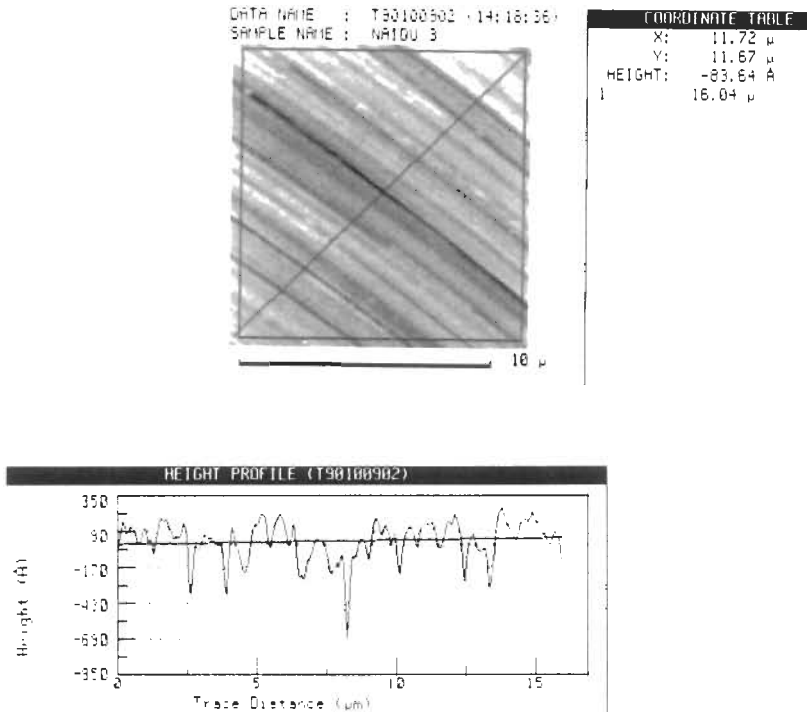


Figure 6 SFM image of a magnetic storage disk demonstrating roughness analysis.

In the magnetic storage disk industry, the technology has advanced to the point where surface roughness differences on the order of a few \AA have become important. Optical and stylus profilometers, while still preferable for scanning very large distances, cannot measure contributions from small features. Figure 6 is an SFM image of a thin-film storage disk (top), shown top-down, with heights displayed in a linear intensity scale (“gray scale”). Using the mouse, the height profile of any cross section can be displayed and analyzed (bottom). Figure 7 shows a thin-film read–write head. The magnetic poles are recessed about 200 \AA ; their roughness is comparable to that of the surrounding medium. Note the textural difference between the glass embedding medium and the ceramic. SFM is not affected by differences in optical properties when it scans composite materials.

Profilometry of softer materials, such as polymers, is also possible with SFM, and with STM if the sample is conducting. Low forces on the SFM tip allow imaging of materials whose surfaces are degraded by traditional stylus profilometry. However, when the surface is soft enough that it deforms under pressure from the SFM tip, resolution will be degraded and topography may not be representative of the true

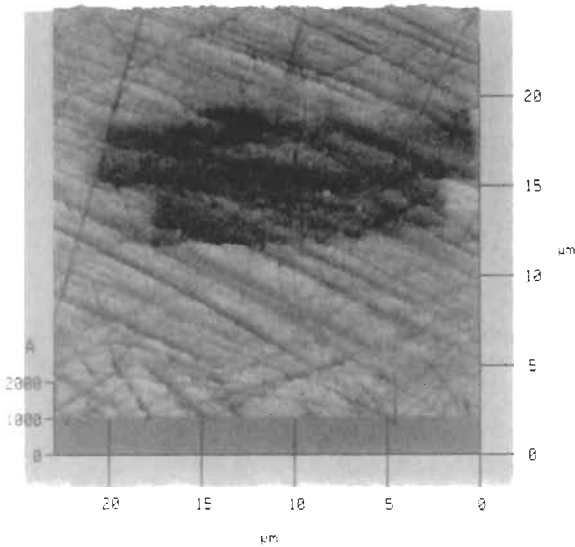


Figure 7 SFM image of a thin-film read-write head showing magnetic poles (dark rectangles) recessed 200 Å.

surface. One can investigate the reproducibility of the image by scanning the sample in different directions at various scan rates and image sizes.

Spectroscopy

The preceding topography and profilometry examples have focused on the scanning force microscope. STM also can be used for topographic imaging and profilometry, but the images will be convolutions of the topographic and electronic structure of the surface. A similar effect is seen with SEM, arising from differences in secondary electron coefficients among different materials.

Taking advantage of the sensitivity of the tunneling current to local electronic structure, the STM can be used to measure the spectra of surface-state densities directly. This can be accomplished by measuring the tunneling current as a function of the bias voltage between the tip and sample, or the conductivity, dI/dV , versus the bias voltage, at specific spatial locations on the surface. Figure 8 is a spectroscopic study of GaAs(110). The image on the left was taken with negative bias voltage on the STM tip, which allows tunneling into unoccupied states, thereby revealing the Ga atoms. Taken simultaneously but with a positive tip bias voltage, the image on the right results from tunneling out occupied states, and shows the positions of the As atoms.

The data above were collected in UHV environment to achieve the most pristine surface. Spectroscopy in air is usually more difficult to interpret due to contamination with oxides and other species, as is the case with all surface-sensitive spectroscopies.

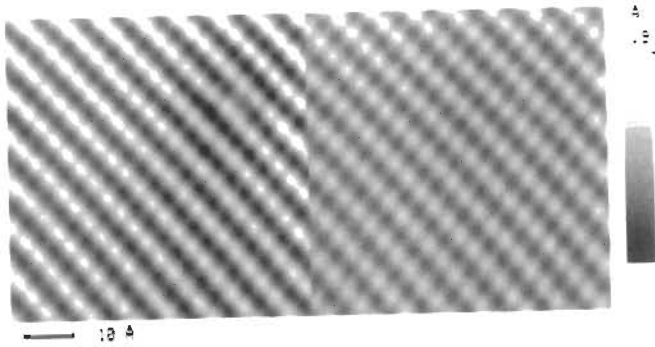


Figure 8 Spectroscopic study of GaAs(110). With a positive voltage on the STM tip, the left-hand image represents As atoms, while the corresponding negative tip voltage on the right shows Ga atoms. (Courtesy of Y. Yang and J.H. Weaver, University of Minnesota)

Sample Requirements

For atomic resolution an atomically flat sample is required to avoid tip imaging (see below). STM requires a conducting surface to establish the tunneling current. Doped Si has sufficient conductivity to enable STM imaging, but surfaces of lower conductivity may require a conductive coating. SFM can image surfaces of any conductivity. Both STM and SFM require solid surfaces that are somewhat rigid; otherwise the probes will deform the surfaces while scanning. Such deformation is easily diagnosed by repeatedly scanning the same area and noting changes.

The deformation of soft surfaces can be minimized with SFM by selecting cantilevers having a low force constant or by operating in an aqueous environment. The latter eliminates the viscous force that arises from the thin film of water that coats most surfaces in ambient environments. This viscous force is a large contributor to the total force on the tip. Its elimination means that the operating force in liquid can be reduced to the order of 10^{-9} N.

An example, Figure 9 is an SFM image of a Langmuir-Blodgett film. This film was polymerized with ultraviolet light, giving a periodicity of 200 Å, which is seen in the associated Fourier transform. The low forces exerted by the SFM tip are essential for imaging such soft polymer surfaces.

Poorly cleaned surfaces may not image well. While ordinary dry dust will be brushed aside by the tip and will not affect the image, oily or partially anchored dirt will deflect the SFM tip or interfere with the conductivity in STM. The result is usually a line smeared in the scan direction, exactly as one would expect if the tip began scanning something which moved as it was scanned. If the sample cannot be cleaned, the best procedure is to search for a clean area.

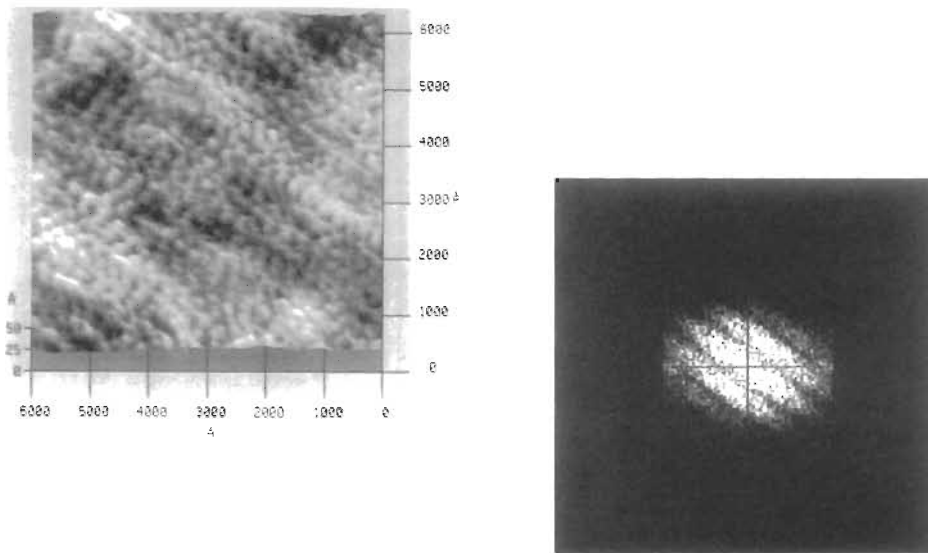


Figure 9 SFM image of Langmuir-Blodgett film (top) and associated Fourier transform (bottom). (Courtesy of T. Kato, Utsunomiya University)

Maximum sample sizes that can be accommodated by SFM or STM vary. Current systems can scan a 8-inch Si wafer without cutting it. When industry calls for the capability to scan larger samples, the SPM manufacturers are likely to respond.

Artifacts

The main body of artifacts in STM and SFM arises from a phenomenon known as *tip imaging*.⁹ Every data point in a scan represents a convolution of the shape of the tip and the shape of the feature imaged, but as long as the tip is much sharper than the feature, the true edge profile of the feature is represented. However, when the feature is sharper than the tip, the image will be dominated by the edges of the tip. Fortunately, this kind of artifact is usually easy to identify.

Other artifacts that have been mentioned arise from the sensitivity of STM to local electronic structure, and the sensitivity of SFM to the rigidity of the sample's surface. Regions of variable conductivity will be convolved with topographic features in STM, and soft surfaces can deform under the pressure of the SFM tip. The latter can be addressed by operating SFM in the attractive mode, at some sacrifice in the lateral resolution. A limitation of both techniques is their inability to distinguish among atomic species, except in a limited number of circumstances with STM microscopy.

STM

In STM, the tip is formed by an atom or cluster of atoms at the end of a long wire. Because the dependence of the tunneling current upon the tip-to-sample distance is exponential, the closest atom on the tip will image the closest atom on the sample. If two atoms are equidistant from the surface, all of the features in the image will appear doubled. This is an example of multiple tip imaging. The best way to alleviate this problem is to collide the tip gently with the sample, to form a new tip and take another image. Alternatively, a voltage pulse can be applied to change the tip configuration by field emission.

STM tips will last for a day or so in ultrahigh vacuum. Most ultrahigh-vacuum STM systems provide storage for several tips so the chamber does not have to be vented just to change tips. In air, tips will oxidize more rapidly, but changing tips is a simple process.

SFM

At present, all commercial SFM tips are square pyramids, formed by CVD deposition of Si_3N_4 on an etch pit in (100) Si. The etch pit is bounded by (111) faces, which means that the resulting tip has an included angle of about 55° . Therefore the edge profiles of all features with sides steeper than 55° will be dominated by the profile of the tip.

Because many kinds of features have steep sides, tip imaging is a common plague of SFM images. One consolation is that the height of the feature will be reproduced accurately as long as the tip touches bottom between features. Thus the roughness statistics remain fairly accurate. The lateral dimensions, on the other hand, can provide the user with only an upper bound.

Another class of artifacts occurs when scanning vertical or undercut features. As the tip approaches a vertical surface, the side wall may encounter the feature before the end of the tip does. The resulting image will appear to contain a discontinuous shift. Changing the angle of the tip with respect to the sample's surface can minimize the problem. Side wall imaging also occurs in STM, but less frequently since an STM tip has a higher aspect ratio than that of an SFM tip.

Improving the aspect ratio of SFM tips is an area of active research. A major difficulty is that the durability of the tip likely will be compromised as aspect ratios are increased.

Conclusions

Scanning probe microscopy is a forefront technology that is well established for research in surface physics. STM and SFM are now emerging from university laboratories and gaining acceptance in several industrial markets. For topographic analysis and profilometry, the resolution and three-dimensional nature of the data is

unequalled by other techniques. The ease of use and nondestructive nature of the imaging are notable.

The main difficulty with STM and SFM techniques is the problem of tip imaging. Neither technique is recommended for obtaining accurate measurements of edge profiles of vertical or undercut surfaces. In addition, SFM tips cannot accurately image the lateral dimensions of features with sides steeper than 55° at present. Obtaining SFM tips with more suitable aspect ratios is an area of active research.

Scanning tunneling and scanning force microscopes are only two members of the family of scanning probe microscopes. Other types of scanning probe microscopes may become widely used in the near future. The magnetic force microscope, for example, may one day be used routinely to study magnetic domains in storage media.

Related Articles in the Encyclopedia

Light Microscopy, SEM, TEM, STEM, and Surface Roughness

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2.4 TEM

Transmission Electron Microscopy

KURT E. SICKAFUS

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- Introduction
- Basic Principles
- TEM Operation
- Specimen Preparation
- Conclusions

Introduction

Transmission Electron Microscopy (TEM) has, in three decades time, become a mainstay in the repertoire of characterization techniques for materials scientists. TEM's strong cards are its high lateral spatial resolution (better than 0.2 nm "point-to-point" on some instruments) and its capability to provide both image and diffraction information from a single sample. In addition, the highly energetic beam of electrons used in TEM interacts with sample matter to produce characteristic radiation and particles; these signals often are measured to provide materials characterization using EDS, EELS, EXELFS, backscattered and secondary electron imaging, to name a few possible techniques.

Basic Principles

In TEM, a focused electron beam is incident on a thin (less than 200 nm) sample. The signal in TEM is obtained from both undeflected and deflected electrons that penetrate the sample thickness. A series of magnetic lenses at and below the sample position are responsible for delivering the signal to a detector, usually a fluorescent screen, a film plate, or a video camera. Accompanying this signal transmission is a

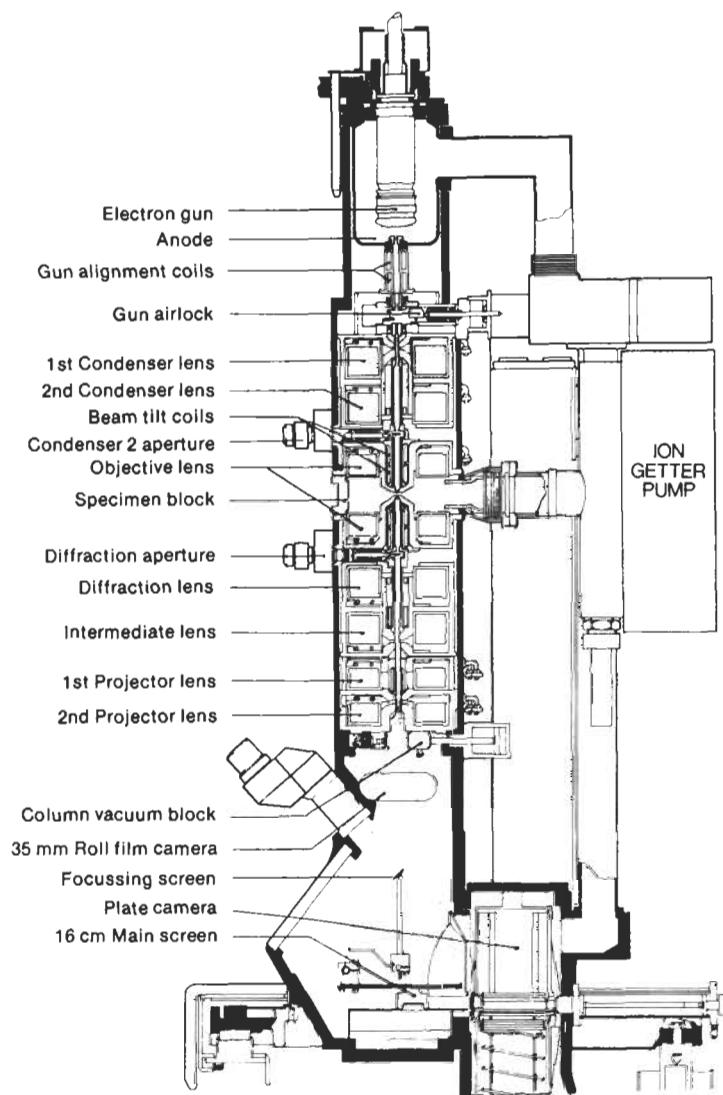


Figure 1a Schematic diagram of a TEM instrument, showing the location of a thin sample and the principal lenses within a TEM column.

magnification of the spatial information in the signal by as little as 50 times to as much as a factor of 10^6 . This remarkable magnification range is facilitated by the small wavelength of the incident electrons, and is the key to the unique capabilities associated with TEM analysis. A schematic of a TEM instrument, showing the location of a thin sample and the principal lenses within a TEM column, is illustrated in Figure 1a. Figure 1b shows a schematic for the ray paths of both unscattered and scattered electrons beneath the sample.

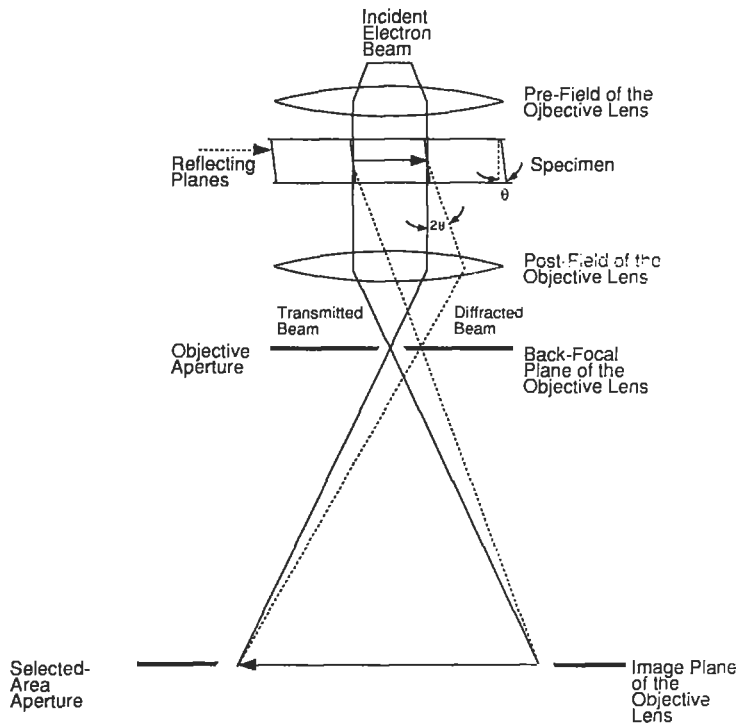


Figure 1b Schematic representation for the ray paths of both unscattered and scattered electrons beneath the sample.

Resolution

The high lateral spatial resolution in a TEM instrument is a consequence of several features of the technique. First, in the crudest sense, TEM has high spatial resolution because it uses a highly focused electron beam as a probe. This probe is focused at the specimen to a small spot, often a μm or less in diameter. More importantly, the probe's source is an electron gun designed to emit a highly coherent beam of monoenergetic electrons of exceedingly small wavelength. The wavelength, λ , of 100 keV electrons is only 0.0037 nm, much smaller than that of light, X rays, or neutrons used in other analytical techniques. Having such small wavelengths, since electrons in a TEM probe are in phase as they enter the specimen, their phase relationships upon exiting are correlated with spatial associations between scattering centers (atoms) within the material. Finally, high lateral spatial resolution is maintained via the use of extremely thin samples. In most TEM experiments, samples are thinned usually to less than 200 nm. For most materials this insures relatively few scattering events as each electron traverses the sample. Not only does this limit spreading of the probe, but much of the coherency of the incident source is also retained.

The higher the operating voltage of a TEM instrument, the greater its lateral spatial resolution. The theoretical instrumental point-to-point resolution is proportional¹ to $\lambda^{3/4}$. This suggests that simply going from a conventional TEM instrument operating at 100 kV to one operating at 400 kV should provide nearly a 50% reduction in the minimum resolvable spacing (λ is reduced from 0.0037 to 0.0016 nm in this case). Some commercially available 300 kV and 400 kV instruments, classified as *high-voltage* TEM instruments, have point-to-point resolutions better than 0.2 nm.

High-voltage TEM instruments have the additional advantage of greater electron penetration, because high-energy electrons interact less strongly with matter than low-energy electrons. So, it is possible to work with thicker samples on a high-voltage TEM. Electron penetration is determined by the mean distance between electron scattering events. The fewer the scattering events, either *elastic* (without energy loss) or *inelastic* (involving energy loss), the farther the electron can penetrate into the sample. For an Al sample, for instance, by going from a conventional 100-kV TEM instrument, to a high-voltage 400 kV TEM instrument, one can extend the mean distance between scattering events (both elastic and inelastic) by more than a factor of 2 (from 90 to 200 nm and from 30 to 70 nm, respectively, for elastic and inelastic scattering).² This not only allows the user to work with thicker samples but, at a given sample thickness, also reduces deleterious effects due to chromatic aberrations (since inelastic scattering is reduced).

One shortcoming of TEM is its limited depth resolution. Electron scattering information in a TEM image originates from a three-dimensional sample, but is *projected* onto a two-dimensional detector (a fluorescent screen, a film plate, or a CCD array coupled to a TV display). The collapse of the depth scale onto the plane of the detector necessarily implies that structural information along the beam direction is superimposed at the image plane. If two microstructural features are encountered by electrons traversing a sample, the resulting image contrast will be a convolution of scattering contrast from each of the objects. Conversely, to identify overlapping microstructural features in a given sample area, the image contrast from that sample region must be deconvolved.

In some cases, it is possible to obtain limited depth information using TEM. One way is to tilt the specimen to obtain a stereo image pair. Techniques also exist for determining the integrated depth (i.e., specimen thickness) of crystalline samples, e.g., using extinction contours in image mode or using convergent beam diffraction patterns. Alternatively, the width or trace of known defects, inclined to the surface of the foil, can be used to determine thickness from geometrical considerations. Secondary techniques, such as EELS and EDS can in some cases be used to measure thickness, either using plasmon loss peaks in the former case, or by modeling X-ray absorption characteristics in the latter. But no TEM study can escape consideration of the complications associated with depth.

Sensitivity

TEM has no inherent ability to distinguish atomic species. Nonetheless, electron scattering is exceedingly sensitive to the target element. Heavy atoms having large, positively charged nuclei, scatter electrons more effectively and to higher angles of deflection, than do light atoms. Electrons interact primarily with the potential field of an atomic nucleus, and to some extent the electron cloud surrounding the nucleus. The former is similar to the case for neutrons, though the principles of interaction are not related, while the latter is the case for X rays. The scattering of an electron by an atomic nucleus occurs by a Coulombic interaction known as Rutherford scattering. This is equivalent to the elastic scattering (without energy loss) mentioned earlier. The scattering of an electron by the electron cloud of an atom is most often an inelastic interaction (i.e., exhibiting energy loss). Energy loss accompanies scattering in this case because an electron in the incident beam matches the mass of a target electron orbiting an atomic nucleus. Hence, significant electron–electron momentum transfer is possible. A typical example of inelastic scattering in TEM is core-shell ionization of a target atom by an incoming electron. Such an ionization event contributes to the signal that is measured in Electron Energy Loss Spectroscopy (EELS) and is responsible for the characteristic X-Ray Fluorescence that is measured in Energy-Dispersive X-Ray Spectroscopy (EDS) and Wavelength-Dispersive X-Ray Spectroscopy (WDS). The latter two techniques differ only in the use of an energy-dispersive solid state detector versus a wavelength-dispersive crystal spectrometer.

The magnitude of the elastic electron–nucleus interaction scales with the charge on the nucleus, and so with atomic number Z . This property translates into image contrast in an electron micrograph (in the absence of diffraction contrast), to the extent that regions of high- Z appear darker than low- Z matrix material in conventional *bright-field* microscopy. This is illustrated in the bright-field TEM image in Figure 2, where high- Z , polyether sulfone ($-\text{C}_6\text{H}_4\text{SO}_2\text{C}_6\text{H}_4\text{O}-$) $_n$ inclusions are seen as dark objects on a lighter background from a low- Z , polystyrene ($-\text{CH}_2\text{CH}(\text{C}_6\text{H}_5)-$) $_n$ matrix. [The meaning of bright field is explained later in this article.]

The probability of interaction with a target atom is much greater for electrons than for X rays, with $f_e \sim 10^4 f_x$ (f_e is the electron atomic scattering factor and f_x is X-ray atomic scattering factor; each is a measure of elemental scattering efficiency or equivalently, the elemental sensitivity of the measurement).³ Unfortunately, with this benefit of elemental sensitivity comes the undesirable feature of multiple scattering. The strong interaction of an incident electron with the potential field of a target atom means that numerous scattering events are possible as the electron traverses the sample. Each scattering event causes an angular deflection of the electron, and often this is accompanied by a loss of energy. The angular deflection upon scattering effectively diminishes the localization of the spatial information in the

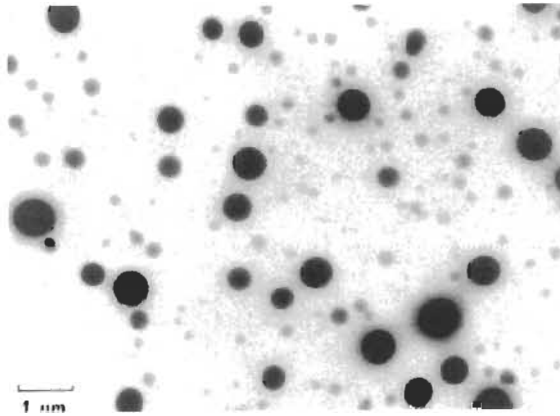


Figure 2 Bright-field TEM image of polyether sulphone inclusions (dark objects; see arrows) in a polystyrene matrix.

TEM signal; the energy losses upon scattering accentuate chromatic aberration effects.

The enormous sensitivity in an electron scattering experiment, in conjunction with the use of a high-brightness electron gun, leads to one of TEM's important features, that of real-time observation. In a conventional TEM, real-time observation is realized by using a W-filament source capable of delivering $\sim 2 \times 10^{19}$ electrons/cm²-s to the specimen,⁴ and a scintillating fluorescent screen to detect the transmitted electrons, viewed through a glass-window flange at the base of the microscope. Recent variations on this theme include the use of better vacuum systems that can accommodate LaB₆ or field-emission gun sources of higher brightness (up to $\sim 6 \times 10^{21}$ electrons/cm²-s),⁴ as well as the use of CCD array-TV displays to enhance detection sensitivity.

TEM Operation

TEM offers two methods of specimen observation, diffraction mode and image mode. In diffraction mode, an electron diffraction pattern is obtained on the fluorescent screen, originating from the sample area illuminated by the electron beam. The diffraction pattern is entirely equivalent to an X-ray diffraction pattern: a single crystal will produce a spot pattern on the screen, a polycrystal will produce a powder or ring pattern (assuming the illuminated area includes a sufficient quantity of crystallites), and a glassy or amorphous material will produce a series of diffuse halos.

The examples in Figure 3 illustrate these possibilities. Figure 3a shows a diffraction pattern from a single crystal Fe thin film, oriented with the [001] crystal axis